

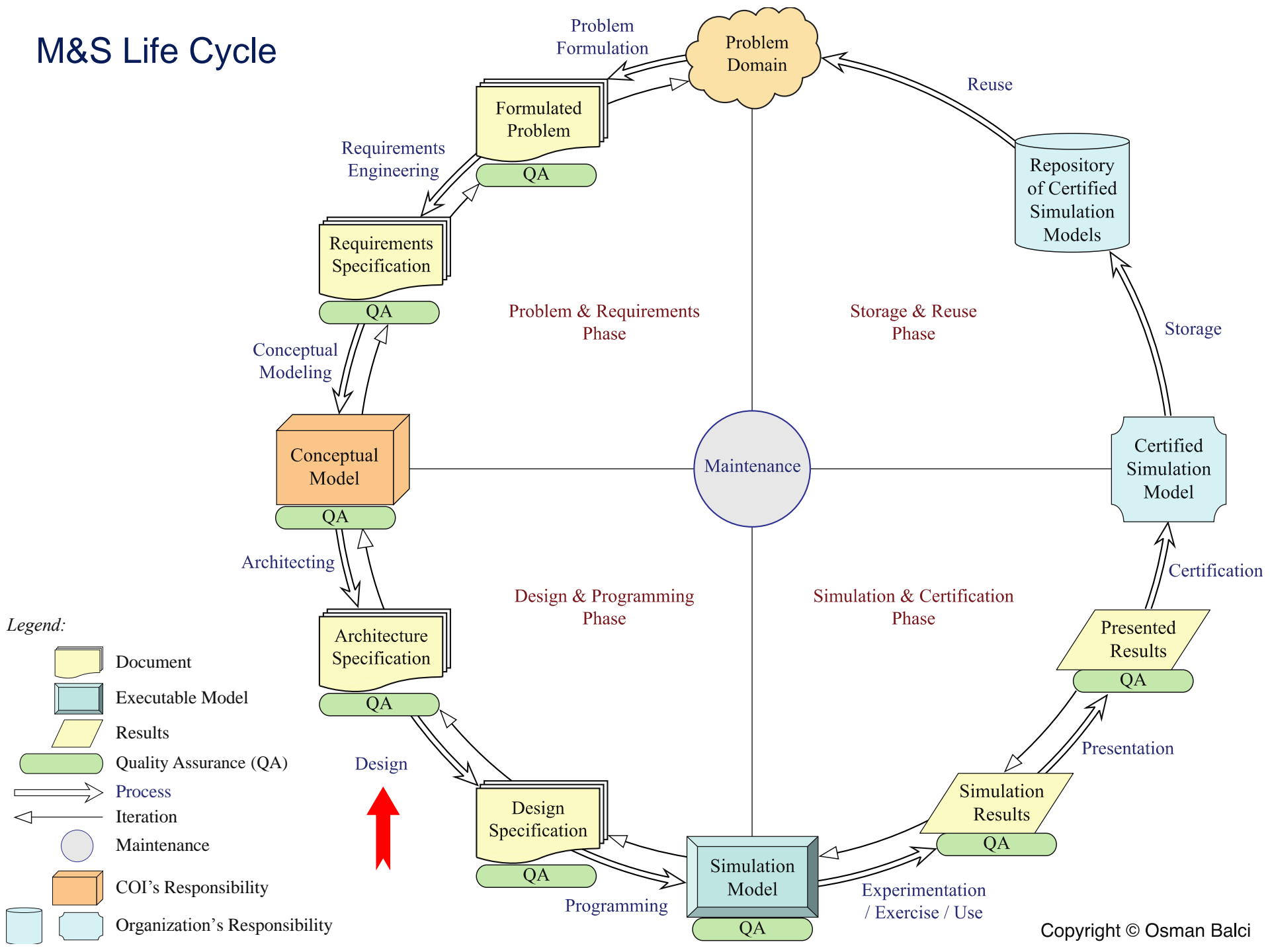
Design of an M&S Application

OSMAN BALCI
Professor

**Department of Computer Science
Virginia Polytechnic Institute and State University (Virginia Tech)
Blacksburg, VA 24061, USA**

<https://manta.cs.vt.edu/balci>

M&S Life Cycle



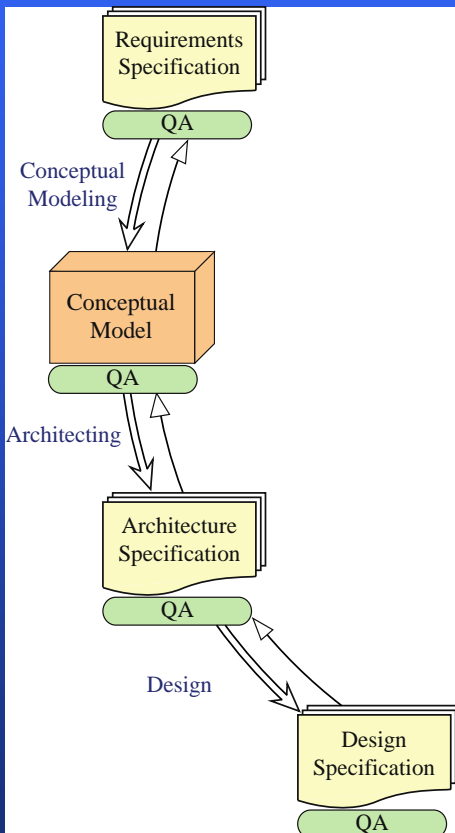
Design

- The **Design** process deals with the instantiation (creation) of a design of the M&S application from the Architecture Specification.

- The **Design** process takes the **M&S Requirements Specification**, **Conceptual Model**, and **Architecture Specification** as input and produces a **design specification** of the M&S application as the output work product.

- **M&S Application Design QA** integrates the assessments of

- a) quality of the M&S application design specification work **product**,
- b) quality of the design **process**,
- c) quality of the **people** employed in the design, &
- d) **project** characteristics related to the life cycle stage for design.



Reuse-based M&S Application Design Using a Conceptual Model (CM)

COI Lead Organization / Sponsor



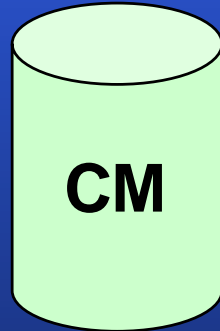
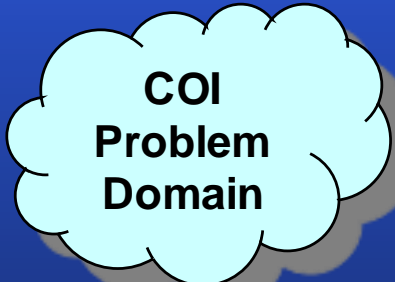
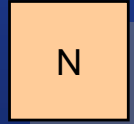
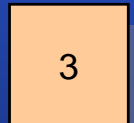
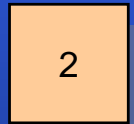
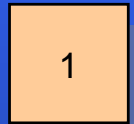
SMEs



M&S Application Designers



M&S Application Designs



Reuse





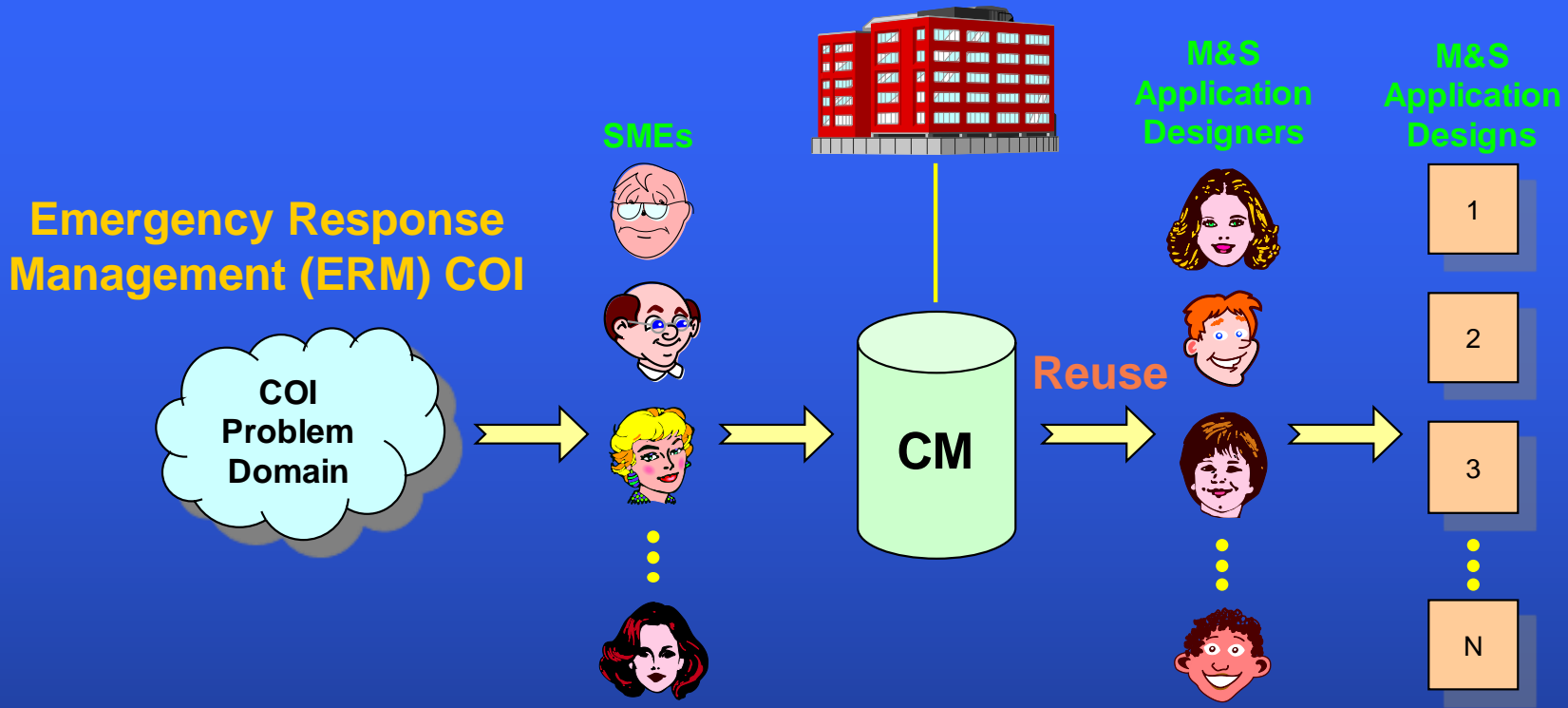
COI
Problem
Domain

- **COI: Emergency Response Management (ERM)**
- **Problem Domain:**
 - Based on the U.S. National Response Plan, states and cities in the U.S. are expected to have an ERM plan.
 - **Problem 1: Asses the operational effectiveness of a given ERM plan.**
 - Under a given ERM plan, first responders, decision makers, authorities involved, and citizens are expected to be trained.
 - **Problem 2: Conduct the training under the ERM plan.**
- **M&S is the only effective approach for solving Problems 1 and 2 above.**

An Example

Federal Emergency Management Agency (FEMA)

COI Lead Organization / Sponsor



- For hundreds of cities and states, there exist hundreds of ERM plans, requiring the development of hundreds of M&S applications for:
 - Assessing the operational effectiveness of an ERM plan.
 - Training first responders, decision makers, authorities involved, and citizens under a given ERM plan.

M&S Application Design Depends on the M&S Area

M&S Areas

A. Based on Model Representation:

1. Discrete M&S
2. Continuous M&S
3. Monte Carlo M&S
4. System Dynamics M&S
5. Gaming-based M&S
6. Agent-based M&S
7. AI-based M&S
8. VR-based M&S

B. Based on Model Execution:

9. Distributed / Parallel M&S
10. Web-based M&S

C. Based on Model Composition:

11. Live Exercises
12. Live Experimentations
13. Live Demonstrations
14. Live Trials

D. Based on What is in the Loop:

15. Hardware-in-the-loop M&S
16. Human-in-the-loop M&S
17. Software-in-the-loop M&S

M&S Application Design Approaches

A. Model Representation:

1. Logic
2. Differential equations
3. Statistical random sampling
4. Rate equations
5. Logic
6. Knowledge, "intelligence"
7. Knowledge, "intelligence"
8. Computer generated visualization

B. Model Execution:

9. Distributed processing / computing
10. Java EE, Microsoft .NET

C. Model Composition:

11. Synthetic environments
12. Synthetic environments
13. Synthetic environments
14. Synthetic environments

D. What is in the Loop:

15. Hardware + Simulation
16. Human + Simulation
17. Software + Simulation

M&S Application Design Depends on the M&S Area

M&S Areas

A. Based on Model Representation:

1. Discrete M&S
2. Continuous M&S
3. Monte Carlo M&S
4. System Dynamics M&S
5. Gaming-based M&S
6. Agent-based M&S
7. AI-based M&S
8. VR-based M&S

B. Based on Model Execution:

9. Distributed M&S
10. Web-based M&S

C. Based on Model Composition:

11. Live Exercises
12. Live Experimentations
13. Live Demonstrations
14. Live Trials

D. Based on What is in the Loop:

15. Hardware-in-the-loop M&S
16. Human-in-the-loop M&S
17. Software-in-the-loop M&S

Discrete M&S Design Approaches:

- Object-Oriented Design
- Procedural Design
 - Procedural Programming
 - Conceptual Frameworks:
 - ❖ Event Scheduling
 - ❖ Activity Scanning
 - ❖ Three-Phase Approach
 - ❖ Process Interaction

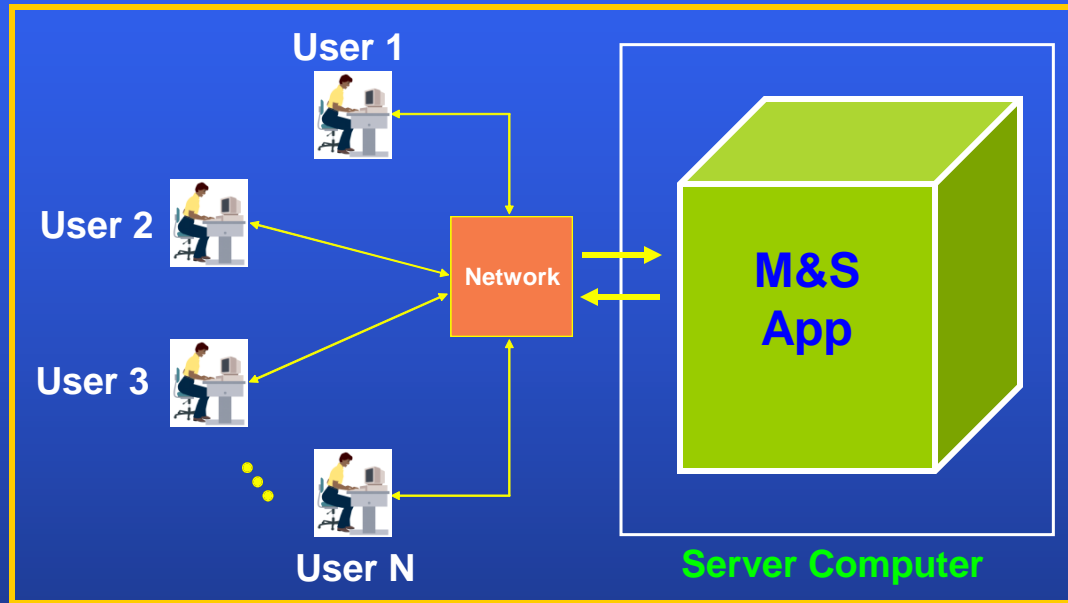
M&S Application Types

- M&S applications can be designed under two categories:
 - **Stand-Alone M&S application**
 - ❖ Intended to run on one computer for a single user
 - ❖ Commonly used for problem solving
 - ❖ Also used for training a single person (e.g., flight simulator)
 - **Network-Centric M&S application**
 - ❖ Intended to run on at least one server computer and used by many people over a network
 - ❖ Ideal for simulations for training people who are geographically dispersed (e.g., OneSAF, JSAF)
 - ❖ Also used for problem solving by many people over a network (e.g., BEST)

Network-Centric M&S Application Design

A design is instantiated (created) from the architecture specified for the M&S application.

Client-Server Architecture



Example:

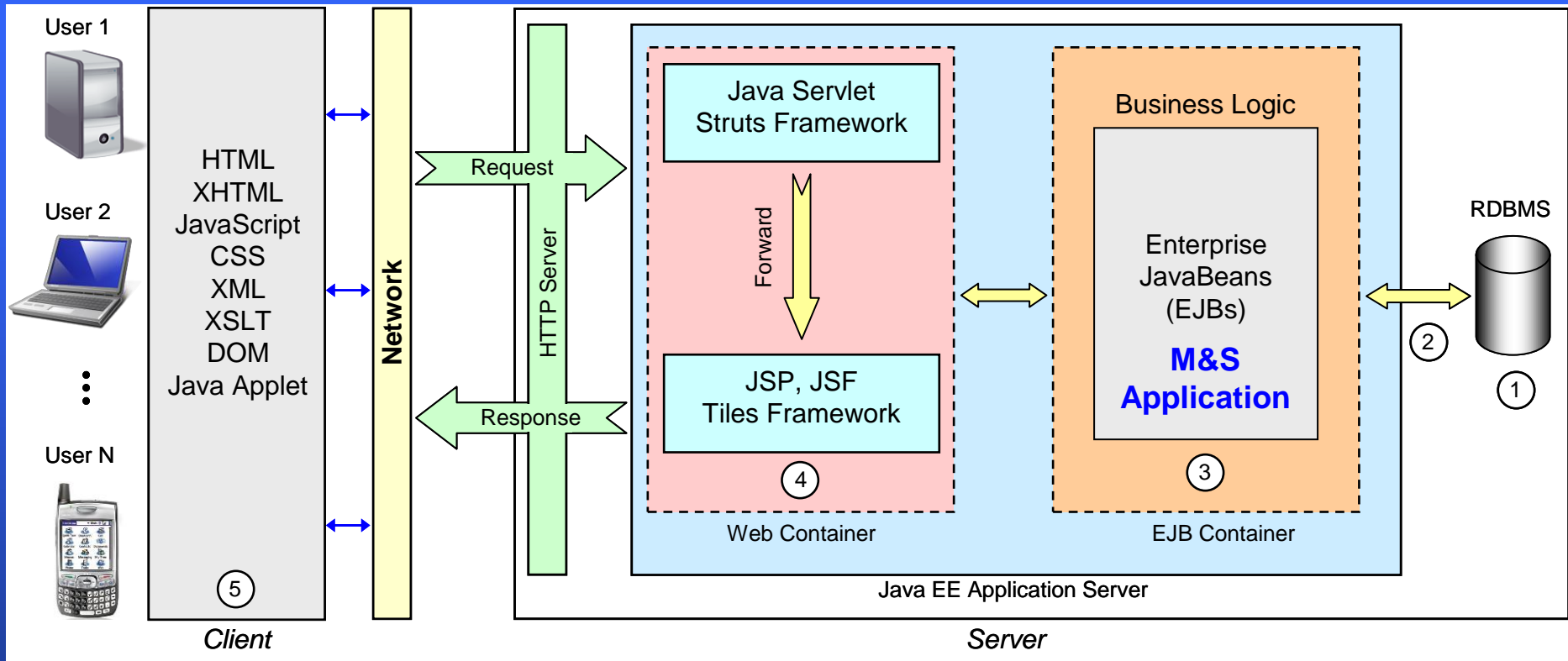
Instantiation

M&S Application Design
based on
the Java Platform
Java Enterprise Edition (EE)

Instantiation

M&S Application Design
based on
the Microsoft Platform
.NET Framework

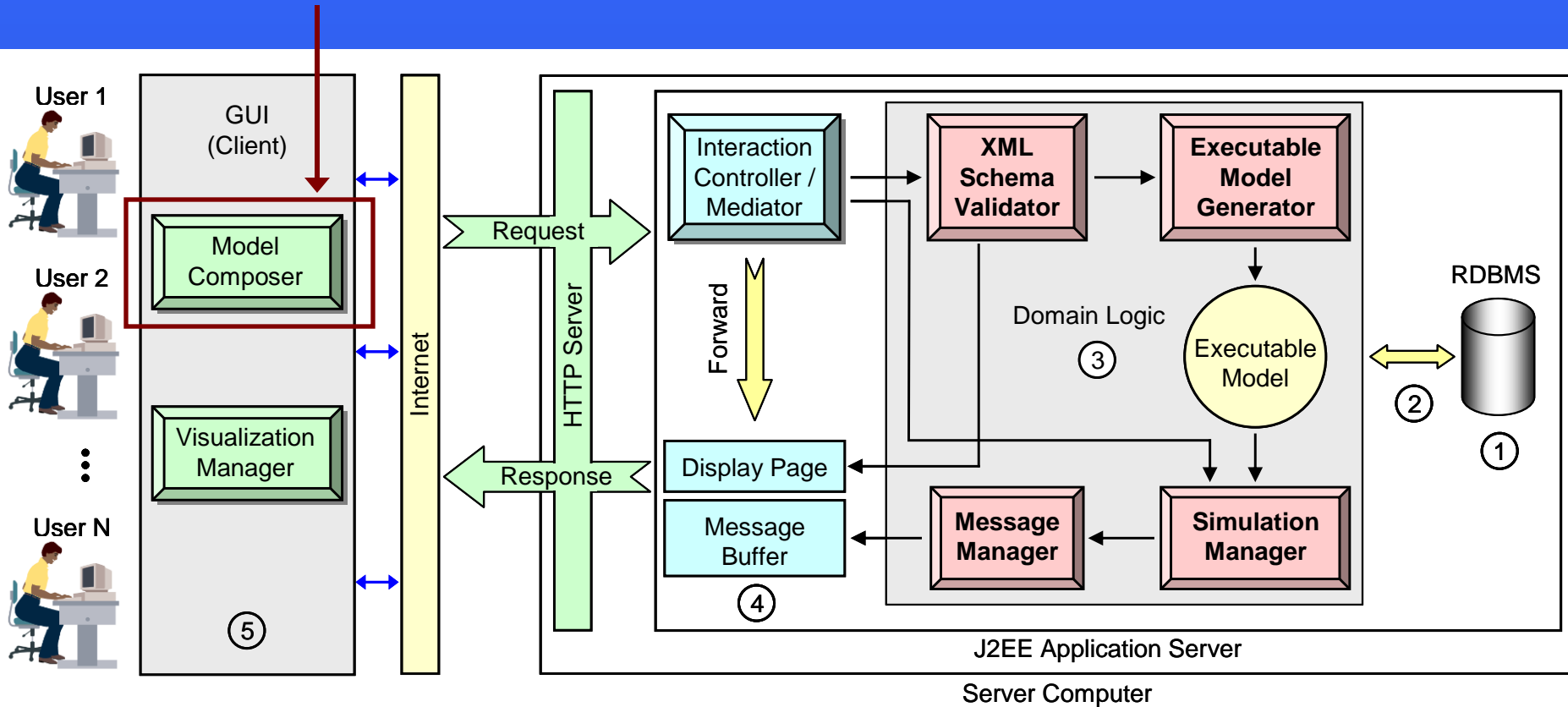
Network-Centric M&S Application Design using the Java Platform



- Java EE architecture layer 3 represents the M&S application core.
- EJBs can be designed and implemented as reusable model components.
- A simulation model can be designed by way of reuse of the EJB model components.

Network-Centric M&S Application Design: WebQS3

Design by way of reuse of components made available in a library.



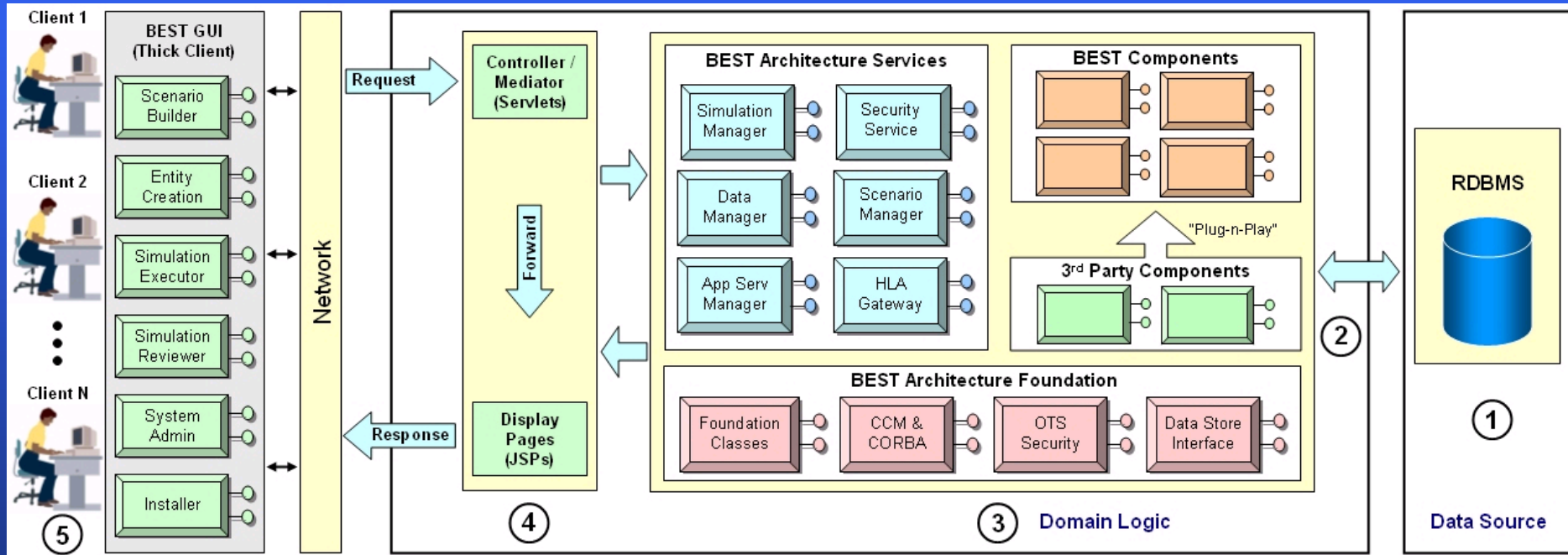
[Play the WebQS3 Editor Video](#)

[Play the WebQS3 Simulator Video](#)

David S. Myers and Osman Balci (2009), "A Web-Based Visual Simulation Architecture," *International Journal of Modelling and Simulation* 29, 2, 137-148.

Network-Centric M&S Application Design: BEST

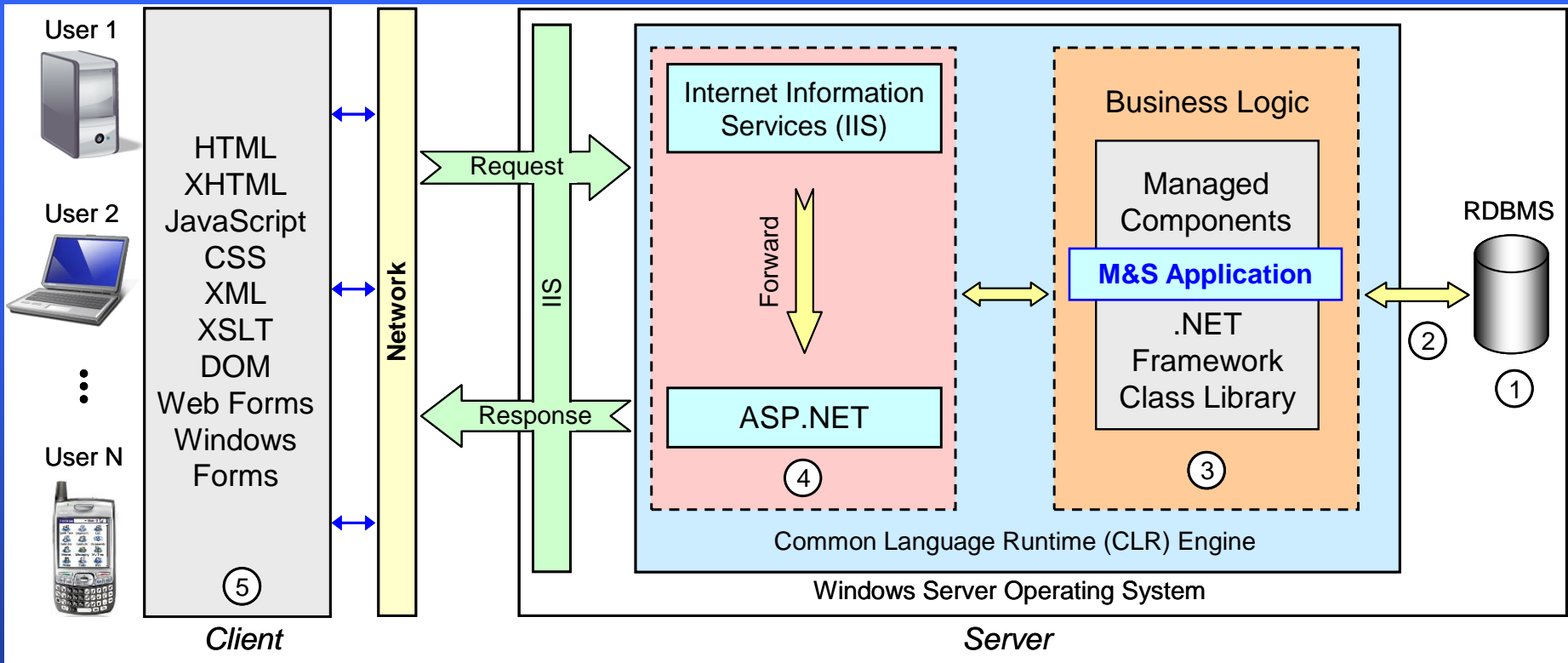
Model Design under the CORBA Distributed Objects Architecture



Java Platform Client-Server Architecture

BEST = Battlespace Environment and Signatures Toolkit
A simulation integrated development environment (IDE)

Network-Centric M&S Application Design using the .NET Framework



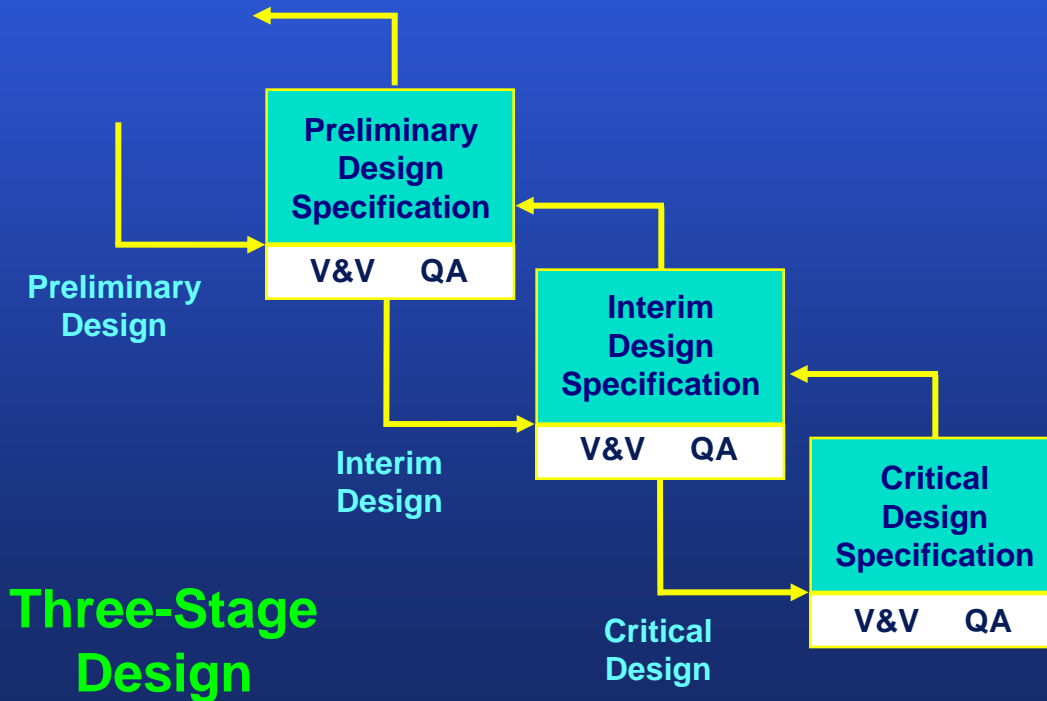
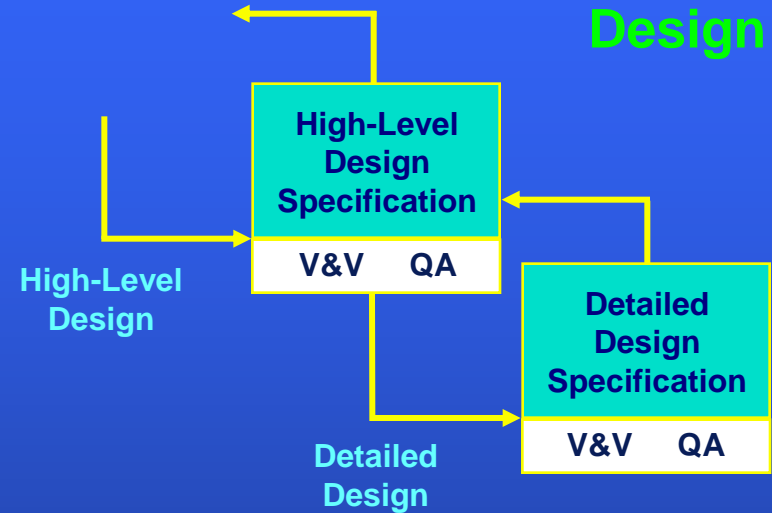
- Microsoft .NET Framework client-server architecture layer 3 represents the M&S application core.
- A simulation model can be designed by using the .NET Framework Class Library.

M&S Application Design Stages

Number of design stages is determined based on the M&S application **complexity**.

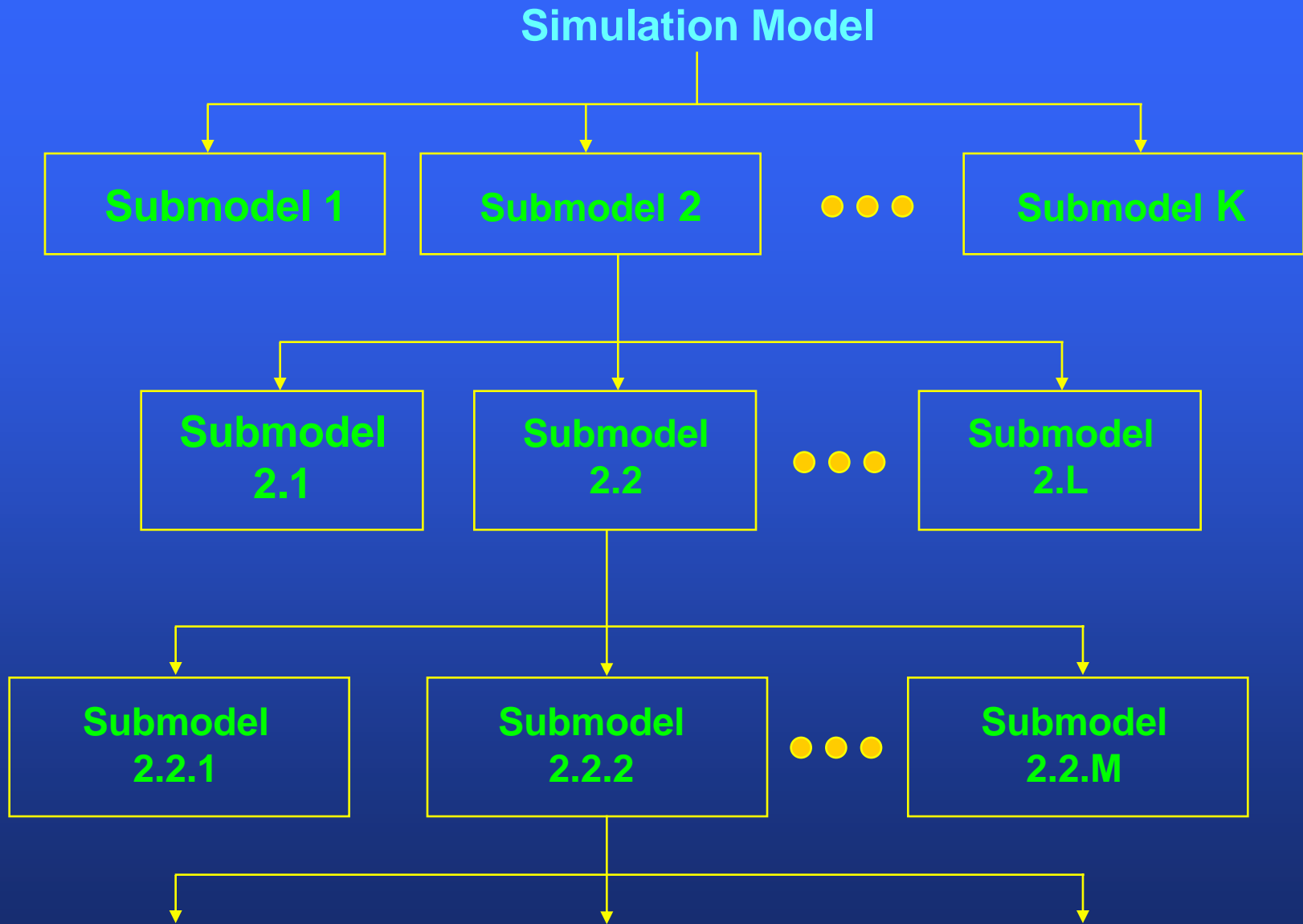


Two-Stage Design



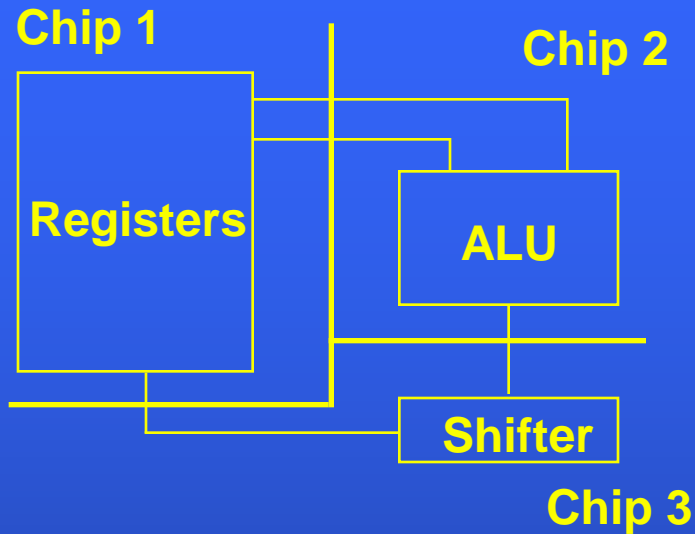
Three-Stage Design

Decomposition / Modularization



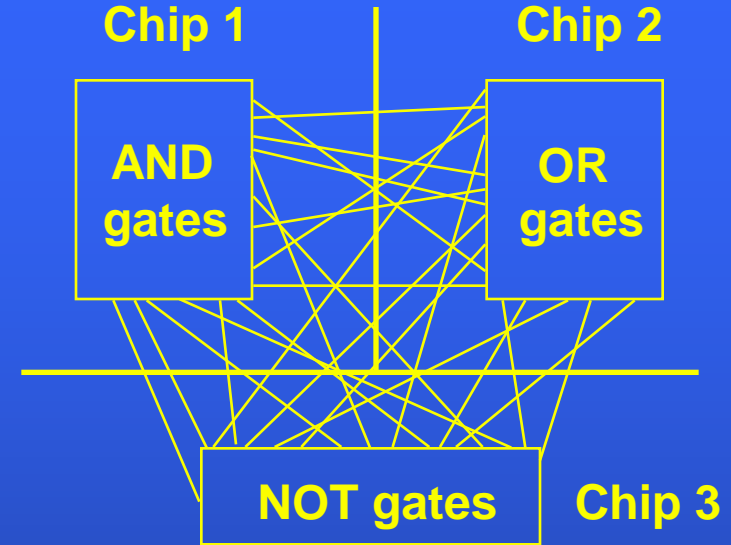
Decomposition / modularization is the key solution to reducing and managing **complexity**.

Design 1



- Functionally same as the other one
- Much easier to understand
- Much easier to modify
- Faults can be localized
- Much easier to **extend** or **enhance**
- Chips can be **reused**
- Maximal relationship within each chip and minimal relationship between chips

Design 2



- Functionally same as the other one
- Much harder to understand
- Much harder to modify
- Faults can not be localized
- Much harder to **extend** or **enhance**
- Chips can not be **reused**
- Minimal relationship within each chip and maximal relationship between chips

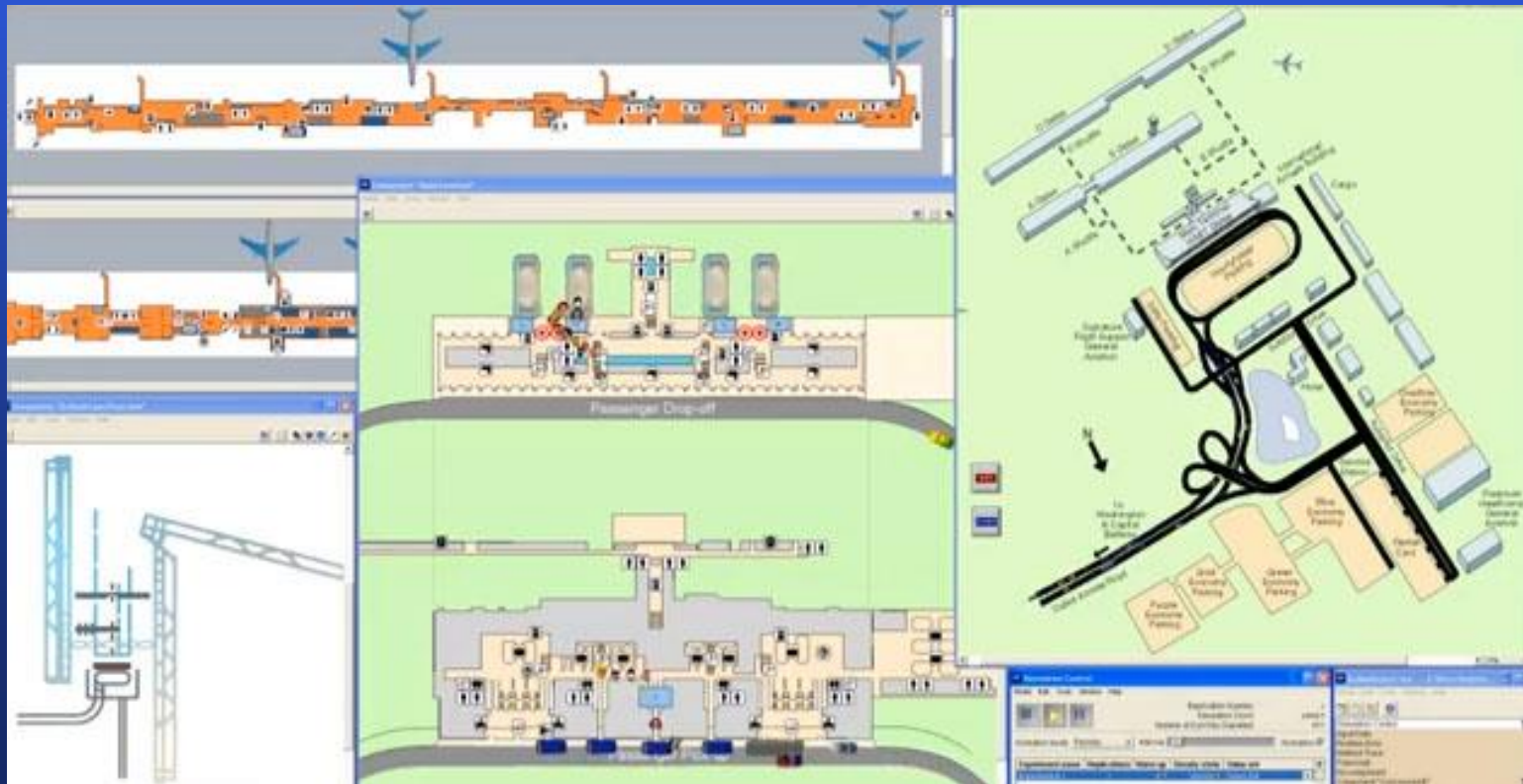
Modularity

- **Objective:** Decompose the simulation model into submodels in such a way as to reduce the cost of maintenance and increase reusability.
- Submodel **COHESION** is the degree of interaction among the elements included within the submodel.
- Submodel **COUPLING** is the degree of dependency between submodels.
- The **maintenance effort is reduced** and **reusability is increased** when there is maximal interaction within each submodel (cohesion) and minimal dependencies (coupling) between submodels.
- **Design Principle:** Design a submodel or model component (class) in such a way that the submodel has
 - the **highest possible cohesion** and
 - the **lowest possible coupling**.

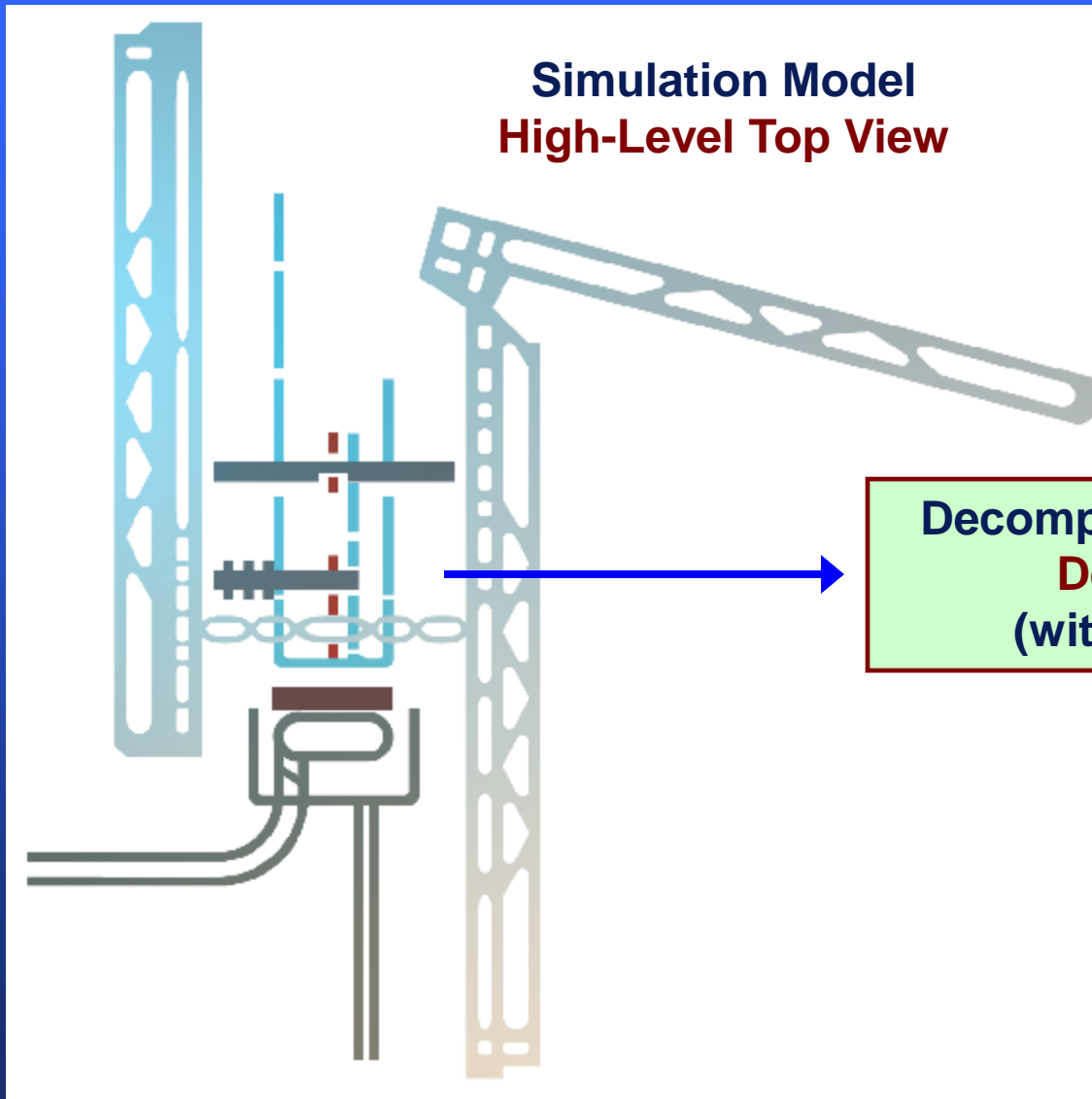
Example Discrete M&S Application Design Using the Object-Oriented Paradigm

Object-Oriented Simulation Model Design of Washington Dulles International Airport

[Click to play the Video of Object-Oriented Visual Simulation of Dulles Airport](#)



Example Decomposition / Modularization: Dulles Airport Simulation



Washington Dulles International Airport, Dulles, Virginia

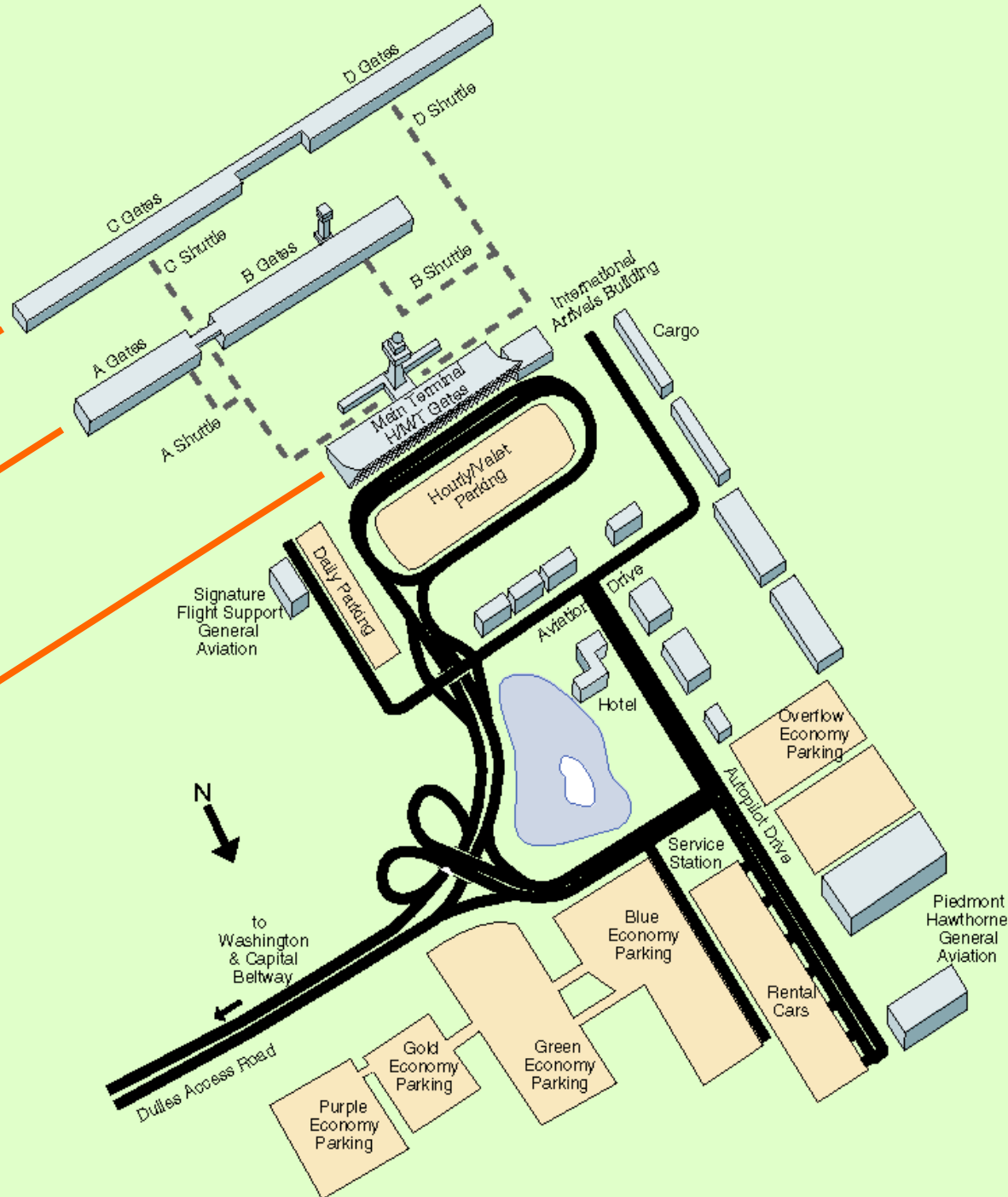
**Submodel
Detailed Top View
(without the runways)**

Decomposed into:

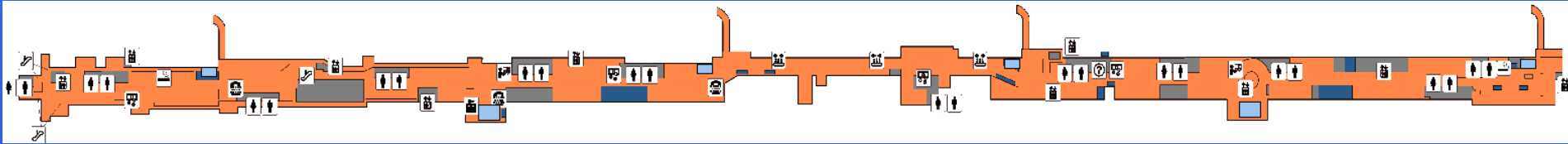
**Concourse CD
submodel**

**Concourse AB
submodel**

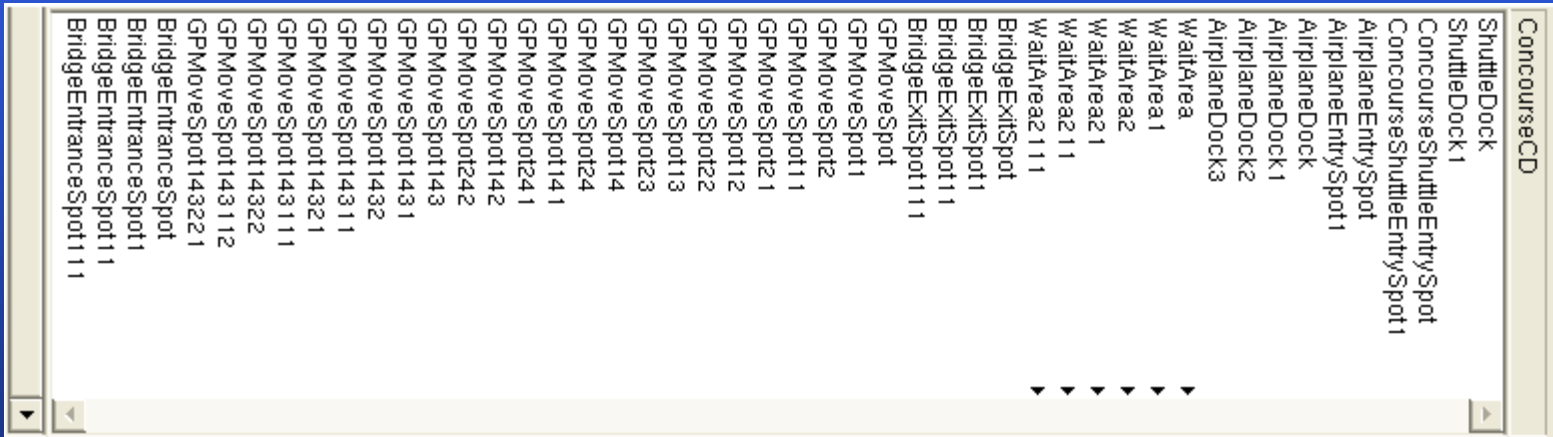
**Main Terminal
submodel**



Submodel Concourse CD

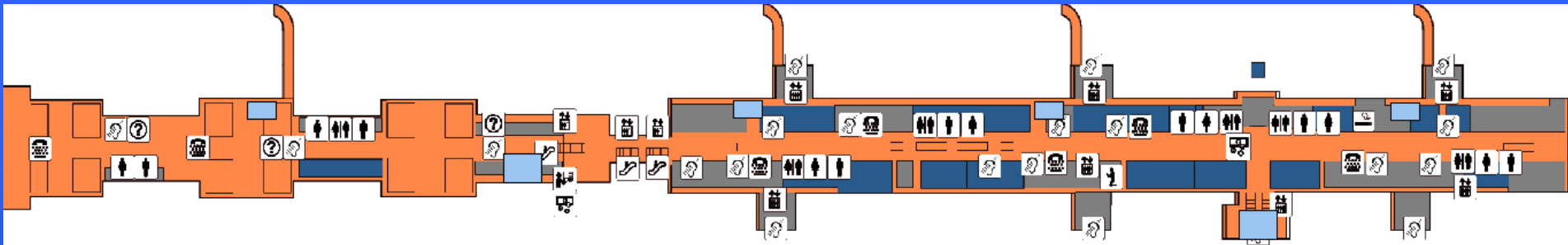


Decomposed into:



Arrows in the submodel browser indicate further decomposition

Submodel Concourse AB



Decomposed into:

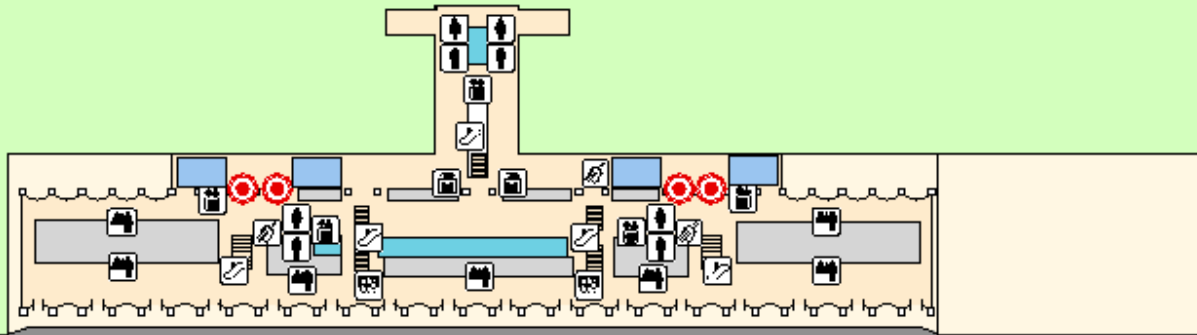


ConcourseAB	
shuttleDockA	
shuttleDockB	
ShuttleEntry/Spot	
ShuttleEntry/Spot 1	
AirplaneEntry/Spot	
AirplaneDock	
AirplaneDock 1	
AirplaneDock 2	
AirplaneDock 3	
AirplaneEntry/Spot 1	
waitArea	
waitArea 1	
waitArea 2	
waitArea 2 1	
waitArea 2 1 1	
waitArea 2 1 2	
GPMove/Spot	
GPMove/Spot 1	
GPMove/Spot 2	
GPMove/Spot 3	
GPMove/Spot 4	
GPMove/Spot 5	
GPMove/Spot 4 1	
GPMove/Spot 4 1 1	
GPMove/Spot 4 1 1 1	
GPMove/Spot 4 1 1 2	
GPMove/Spot 4 1 1 1 1	
GPMove/Spot 4 1 1 3	
GPMove/Spot 4 1 1 1 2	
GPMove/Spot 4 1 1 3 1	
GPMove/Spot 4 1 1 1 2 1	
GPMove/Spot 4 1 1 3 1 1	
GPMove/Spot 4 1 1 3 2	
GPMove/Spot 3 1	
GPMove/Spot 4 1 2	
GPMove/Spot 4 1 1 3 2 1	
BridgeEntrance/Spot	
BridgeEntrance/Spot 1	
BridgeEntrance/Spot 1 1	
BridgeEntrance/Spot 1 2	

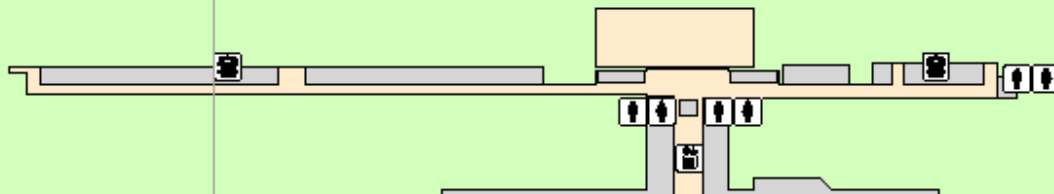


Arrows in the submodel browser indicate further decomposition

Submodel Main Terminal



Passenger Drop-off

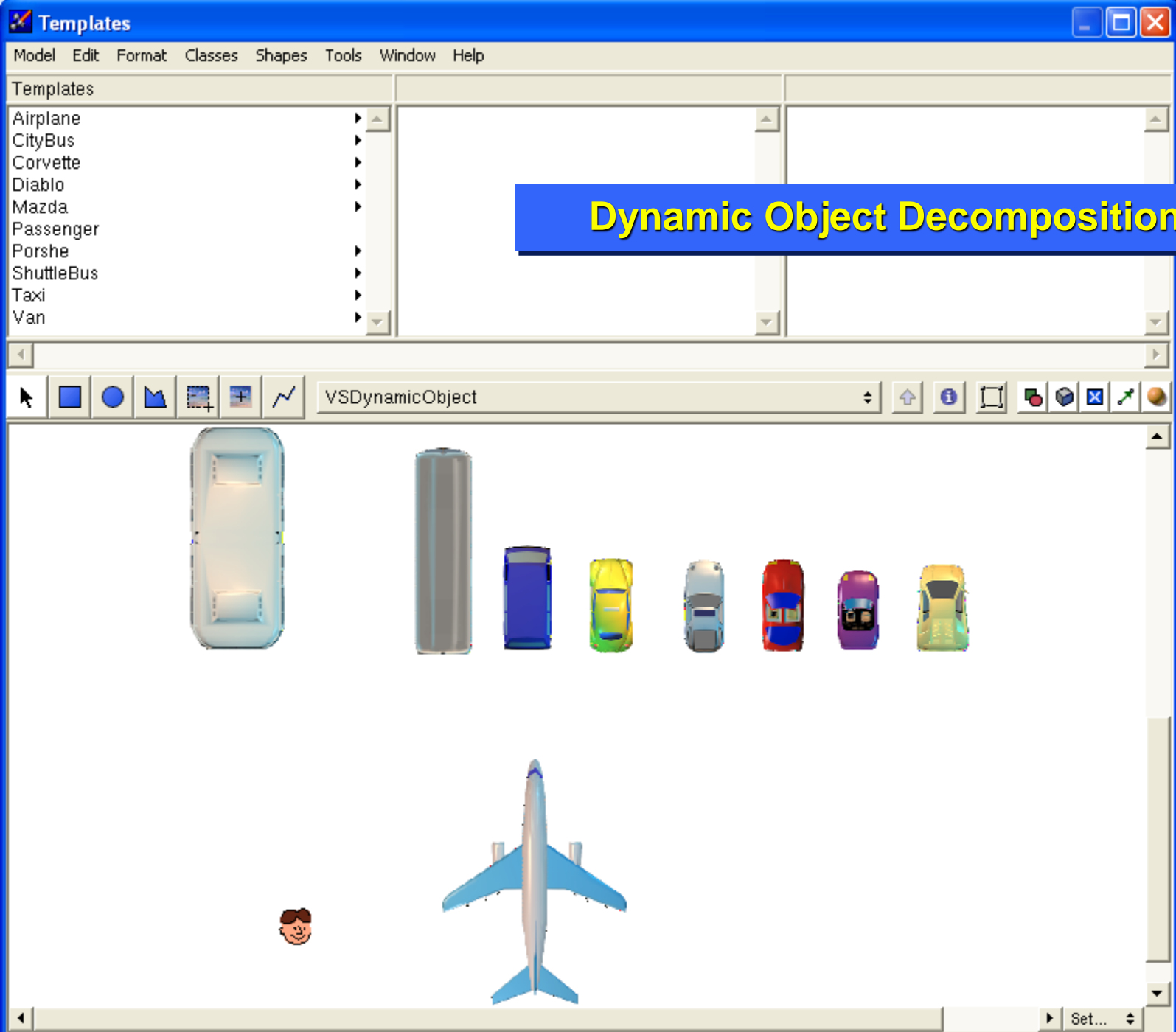


Passenger Pick-up

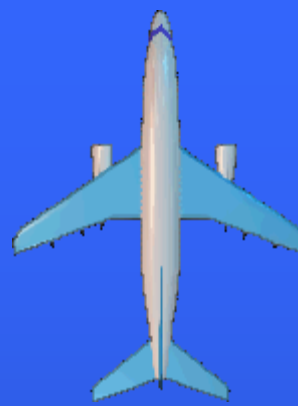


MainTerminal

- DropOffBeginning
- PickUpBeginning
- DropOffSpot
- DropOffSpot1
- DropOffSpot2
- DropOffSpot3
- DropOffSpot4
- DropOffSpot5
- DropOffSpot6
- PickUpSpot
- PickUpSpot1
- PickUpSpot2
- PickUpSpot3
- PickUpSpot4
- PickUpSpot5
- PickUpSpot6
- GPMoveSpot
- GPMoveSpot1
- GPMoveSpot3
- GPMoveSpot5
- GPMoveSpot6
- GPMoveSpot8
- GPMoveSpot12
- GPMoveSpot19
- ShuttleDock
- ShuttleDock1
- ShuttleDock2
- ShuttleDock3
- GPMoveSpot2
- ShuttleEntrySpot
- ShuttleEntrySpot1
- ShuttleEntrySpot2
- ShuttleEntrySpot3
- GPMoveSpot4
- GPMoveSpot7
- GPMoveSpot9
- GPMoveSpot10
- GPMoveSpot11
- GPMoveSpot13
- GPMoveSpot14
- GPMoveSpot15
- GPMoveSpot16
- GPMoveSpot17
- GPMoveSpot17.1
- GPMoveSpot17.11
- GPMoveSpot17.12
- GPMoveSpot17.13
- GPMoveSpot17.121
- GPMoveSpot17.122
- GPMoveSpot17.1211
- GPMoveSpot17.12111
- GPMoveSpot17.12112
- GPMoveSpot17.12113
- GPMoveSpot17.12114
- GPMoveSpot17.121131
- Component
- Component1
- Component2
- Component3
- GPMoveSpot17.121121
- GPMoveSpot17.1211211
- GPMoveSpot17.12112111



Dynamic Object Airplane Decomposition

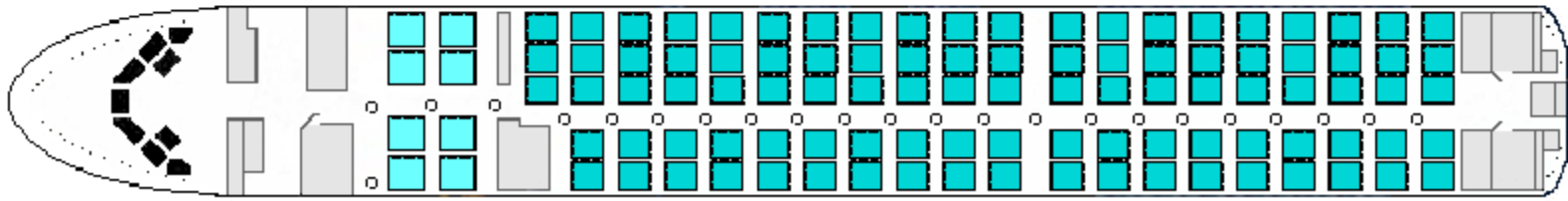


Templates - Airplane

Model Edit Format Classes Shapes Tools Window Help

Templates	Airplane
Airplane	Move Spot3
CityBus	Move Spot4
Corvette	Move Spot5
Diablo	Move Spot6
Mazda	Move Spot7
Passenger	Move Spot8
Porsche	Move Spot9
ShuttleBus	Seat - 10A
Taxi	Seat - 10B
Van	Seat - 10C
	Seat - 10D
	Seat - 10E
	Seat - 11A

VSDynamicObject



40%

Dynamic Object Shuttle Bus Decomposition



Templates - ShuttleBus

Model Edit Format Classes Shapes Tools Window Help

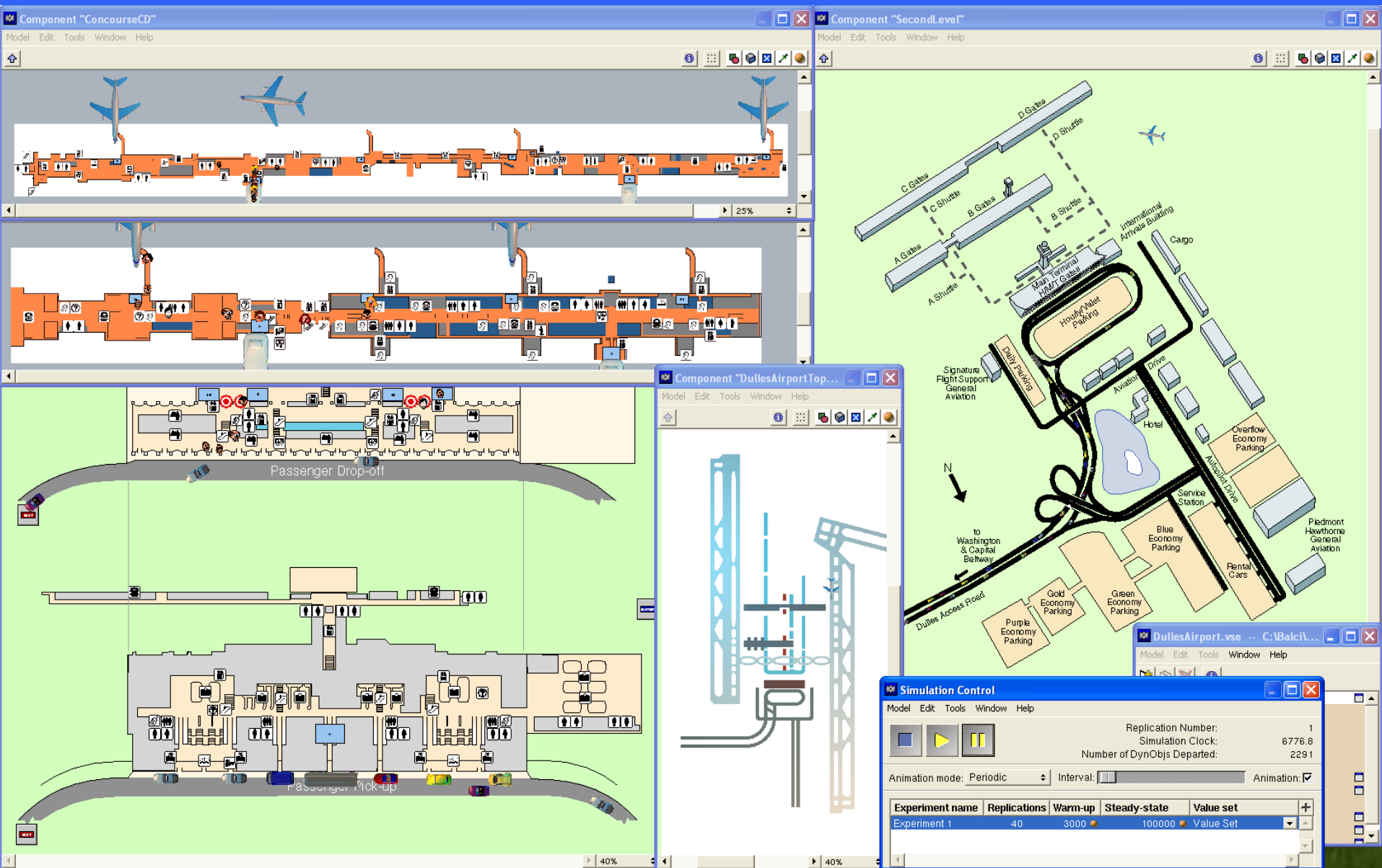
Templates	ShuttleBus
Airplane	GPDoor
CityBus	GPMoveSpot
Corvette	GPMoveSpot1
Diablo	GPMoveSpots5
Mazda	GPMoveSpots6
Passenger	Seat 1
Porshe	Seat 10
ShuttleBus	Seat 11
Taxi	Seat 12
Van	Seat 13
	Seat 14
	Seat 15

VSDynamicObject

40%

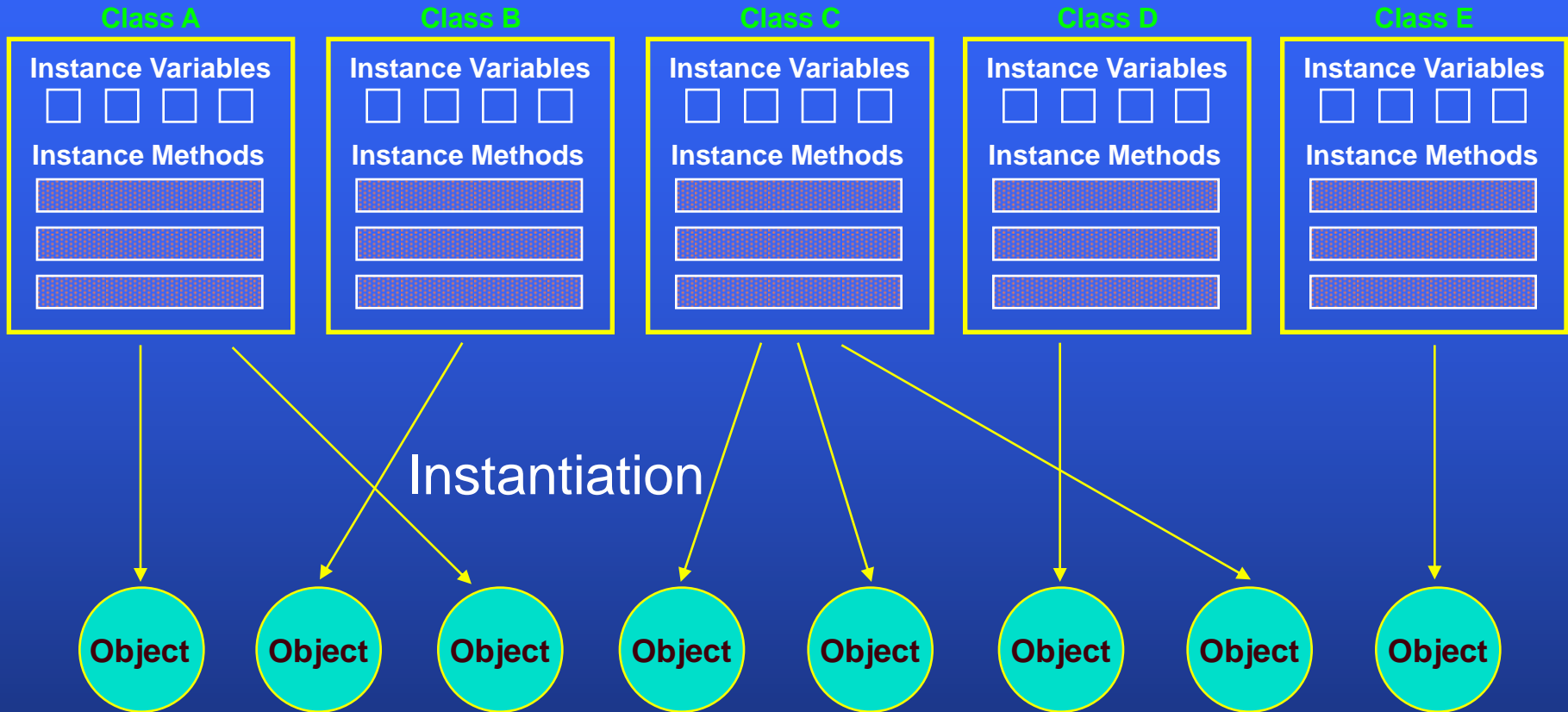
Dulles Airport Visual Simulation

[Click to play the Video of Object-Oriented Visual Simulation of Dulles Airport](#)



Discrete M&S Design using the Object-Oriented Paradigm

Classes are created at design time.



Some objects are created (instantiated) at design time and some at execution time.

Interactions among objects take place via **message passing** during execution.

Object-Oriented Simulation Model Design

- **Objects**
- **Classes**
- **Instantiation**
- **Variables (Attributes)**
- **Methods (Services, Operations)**
- **Inheritance**
- **Message Passing**
- **Encapsulation**
- **Polymorphism**
- **Dynamic Binding**

Objects

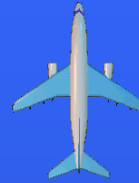
Examples:



Passenger



Car



Airplane

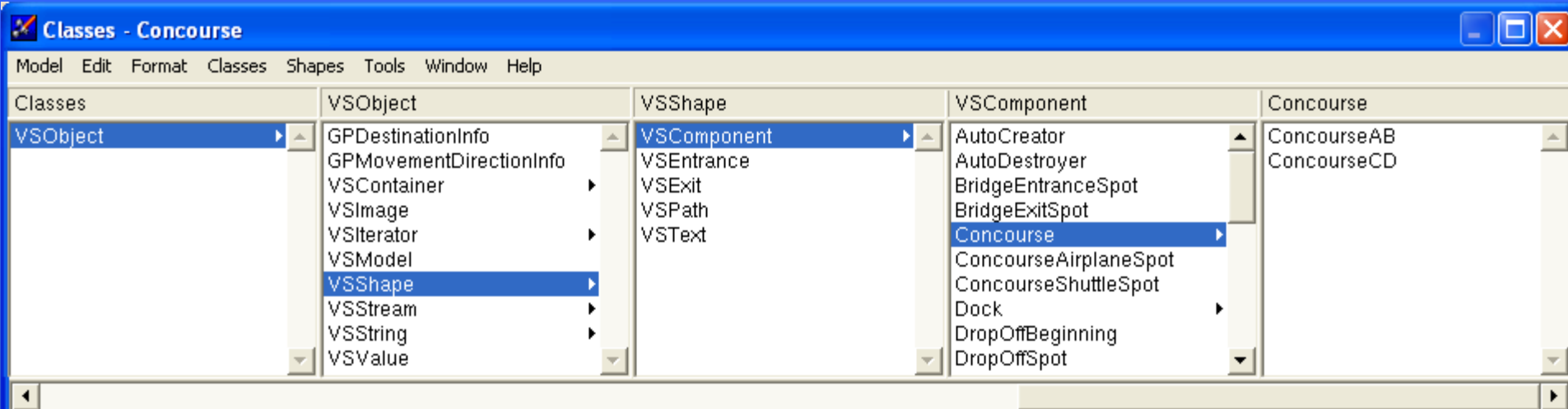


Shuttle
Bus

- Runway
- Dock
- Main Terminal
- Concourse
- Wait Area

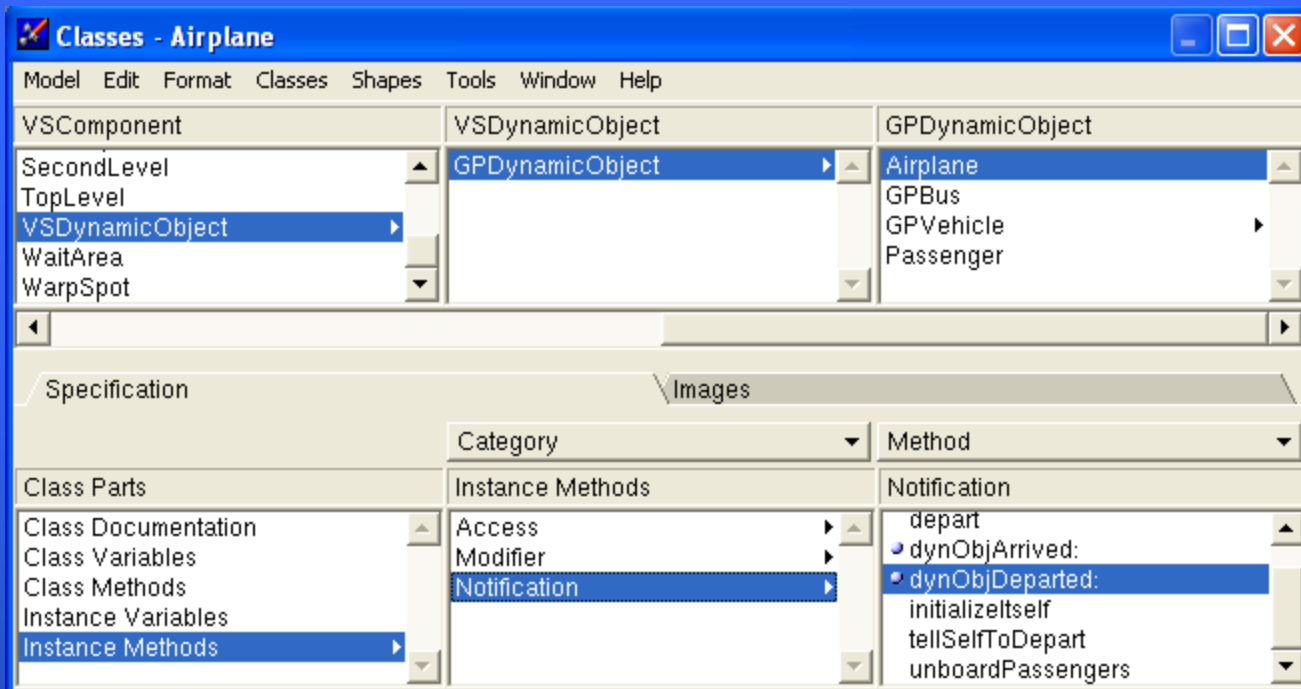
- An **object** is an entity which has a state and a defined set of operations which operate on that state.
- The state is represented as a set of object attributes.
- The operations associated with the object provide services to other objects (clients) which request these services when needed.
- Objects are created according to some object class definition.
- An object class definition serves as a template for objects. It includes declarations of all the attributes and services which should be associated with an object of that class.

Classes



- A **class** is a grouping or categorization of objects with the same characteristics, services, and behaviors.
- A class may be extended into other classes. Extending a class is called **subclassing** and an extended class is called a **subclass**.
- A **subclass** inherits all the characteristics, services, and behaviors of the parent class.
- It customizes what it inherits and/or provides more characteristics, services, or behaviors.
- The parent of a subclass is called the **superclass**.
- The top class having no superclass is called the **root class**.

Instantiation



- Creation of an object belonging to a class is called **instantiation**.
- The new object **inherits** all characteristics (**instance variables**) and behaviors (**instance methods**) specified in the class from which it is instantiated.
- Instance variables of a class are created for each object instantiated as a member of that class.
- Instance methods are inherited, but no method code is replicated.

Variables (Attributes)

- Characteristics (attributes) of an object are represented by variables. Typically three kinds of variables exist: class variables, instance variables, and local variables.
- **Class Variables** are attributes of a class and are declared in the class for use by the methods of that class and its subclasses and by the objects instantiated from that class and its subclasses.
- **Instance Variables**, declared in a class, are used by the instance methods of that class and are created for each object instantiated as belonging to that class or any of its subclasses, i.e., for each instance of a class, and hence the designator “instance”.
- **Local Variables** are declared within a method for use only during the execution of that method. On completion of a method, all local variable values are lost.
- **Example variables can have the following data types:**
 - boolean, character, class reference, object reference, integer number, real number, enumeration.

Example Instance Variables

The screenshot shows a software development environment window titled "Classes - Airplane". The window has a menu bar with "Model", "Edit", "Format", "Classes", "Shapes", "Tools", "Window", and "Help". Below the menu bar are three panes: "VComponent", "VSDynamicObject", and "GPDynamicObject". The "VComponent" pane lists several classes, with "VSDynamicObject" selected. The "VSDynamicObject" pane lists "GPDynamicObject", which is selected. The "GPDynamicObject" pane lists "Airplane", "GPBus", "GPVehicle", and "Passenger", with "Airplane" selected. Below these panes is a "Specification" section with a "Category" dropdown set to "Method". The "Class Parts" section is visible, with "Instance Variables" selected. The "Instance Variables" section shows a list of variables with their types and names:

Type	Variable Name
real	departureTime;
VSList ref	seatList;
integer	nextSeatNumber;
GPMoveSpot ref	door;
VSStrng ref	gateName;
VSStrng ref	oldGateName;
boolean	initializing;
boolean	arriving;

Methods (Services)

- Services provided and behaviors exhibited by an object are specified in methods. Two types of methods exist: class methods and instance methods.
- **Class Methods** are used to provide services specific to a class. For example, the method “new” which creates an instance of a class.
- **Instance Methods**, given in a class, are used to specify the services provided and behavior exhibited for each object instantiated from that class.
- Each instance (i.e., instantiated object) created as belonging to a class provides the services and behavior specified in the instance methods of that class.
- The method code is specified only once in the class and is not replicated for each instantiation of an object from that class.

Example Instance Methods

The screenshot shows the 'Classes - Airplane' window with the following structure:

- Model:** VSDynamicObject, GPDynamicObject, GPDynamicObject
- Edit:** TopLevel, VSDynamicObject, WaitArea, WarpSpot
- Format:** (empty)
- Classes:** (empty)
- Shapes:** (empty)
- Tools:** (empty)
- Window:** (empty)
- Help:** (empty)

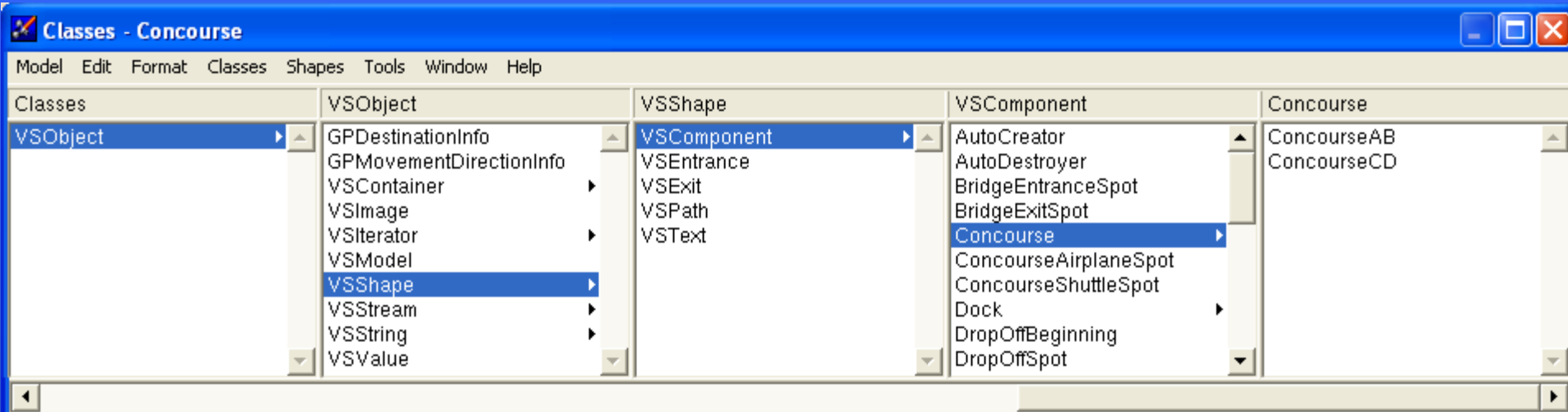
Specification

Category	Method
Class Parts	Notification
Class Documentation	checkPassengers
Class Variables	depart
Class Methods	• dynObjArrived:
Instance Variables	• dynObjDeparted:
Instance Methods	initializeSelf
	tellSelfToDepart

Documentation | **Logic**

```
returns
  nothing
parameters
  none
declarations
  none
logic
  if [numberOfDynObjs] <> 0 then
  {
    tell self to unboardPassengers;
  }
  else //start boarding since airplane is empty
  {
    if ([location] <> nil ) then
    {
      set nextSeatNumber to 1;
      tell [location] to requestPassengersFromWaitArea:NUMBER_OF_SEATS;
      tell self to performMessageNamed:"depart" afterTime:(airplaneWaitTime+20);
    }
  }
}
```

Inheritance



- When an object is declared as member of a class, it **inherits** the characteristics (instance variables) and behaviors (instance methods) of that class as well as the characteristics and behaviors of that class's superclass, and any ancestral classes, tracing back to the root class.
- **Inheritance significantly facilitates reusability of earlier developed classes and decreases simulation model development time.**

logic

```
if [numberOfDynObjs] <> 0 then
{
    tell self to unboardPassengers;
}
else //start boarding since airplane is empty
{
    if ([location] <> nil ) then
    {
        set nextSeatNumber to 1;
        tell [location] to requestPassengersFromWaitArea:NUMBER_OF_SEATS;
        tell self to performMessageNamed:"depart" afterTime:(airplaneWaitTime+20);
    }
}
}
```

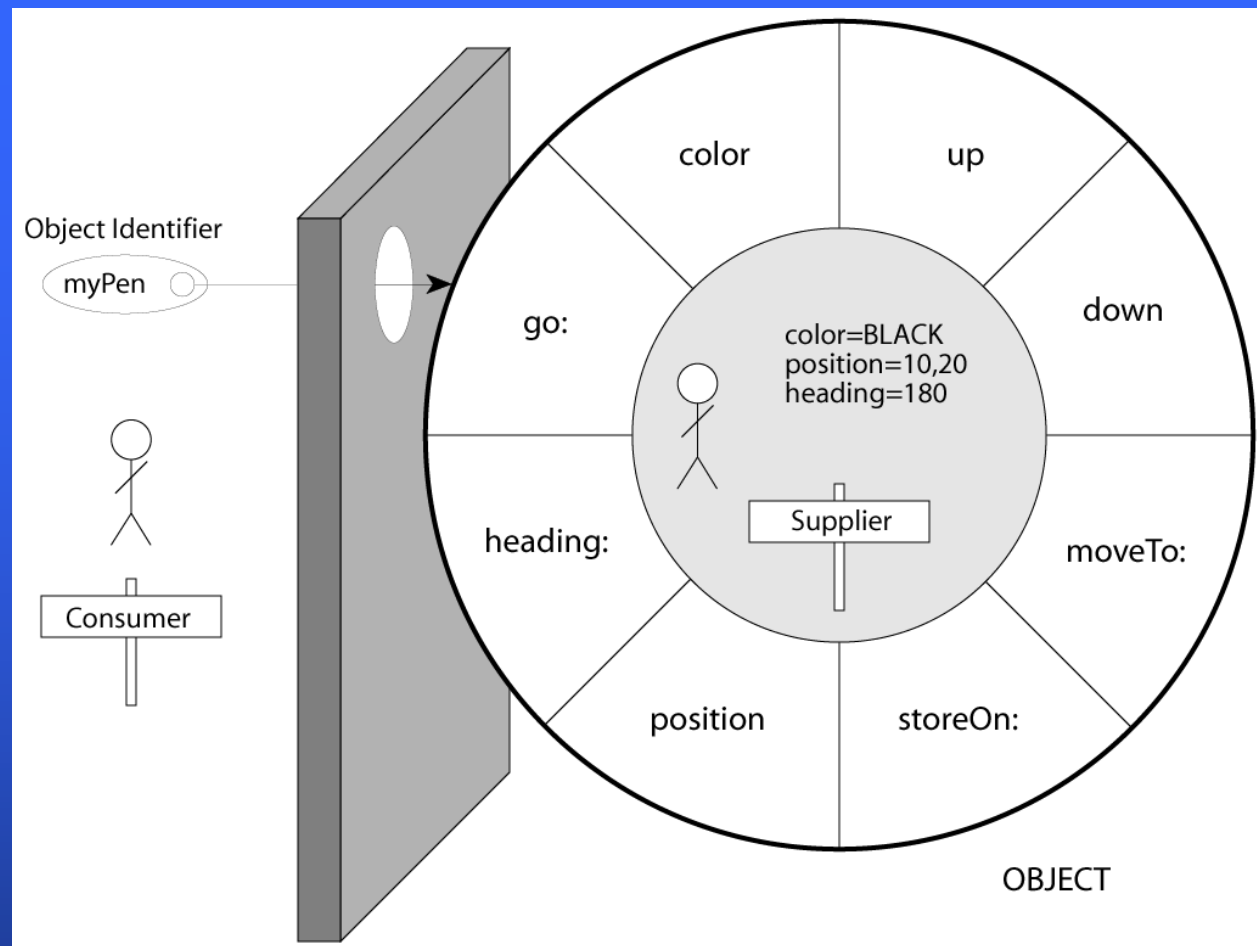
Message Passing

Airplane object's
checkPassengers method logic

- All objects communicate with each other via message passing.
- Sending a message to an object implies the invocation of one of the receiving object's methods.
- Generally, it is said that “**send message M to object A**” as opposed to “**send a message to object A to invoke its method M.**”
- Objects are identified by their unique addresses internally maintained by the implementation programming language. They are called **object references**. An object reference uniquely identifies the object which will receive the message.

Encapsulation

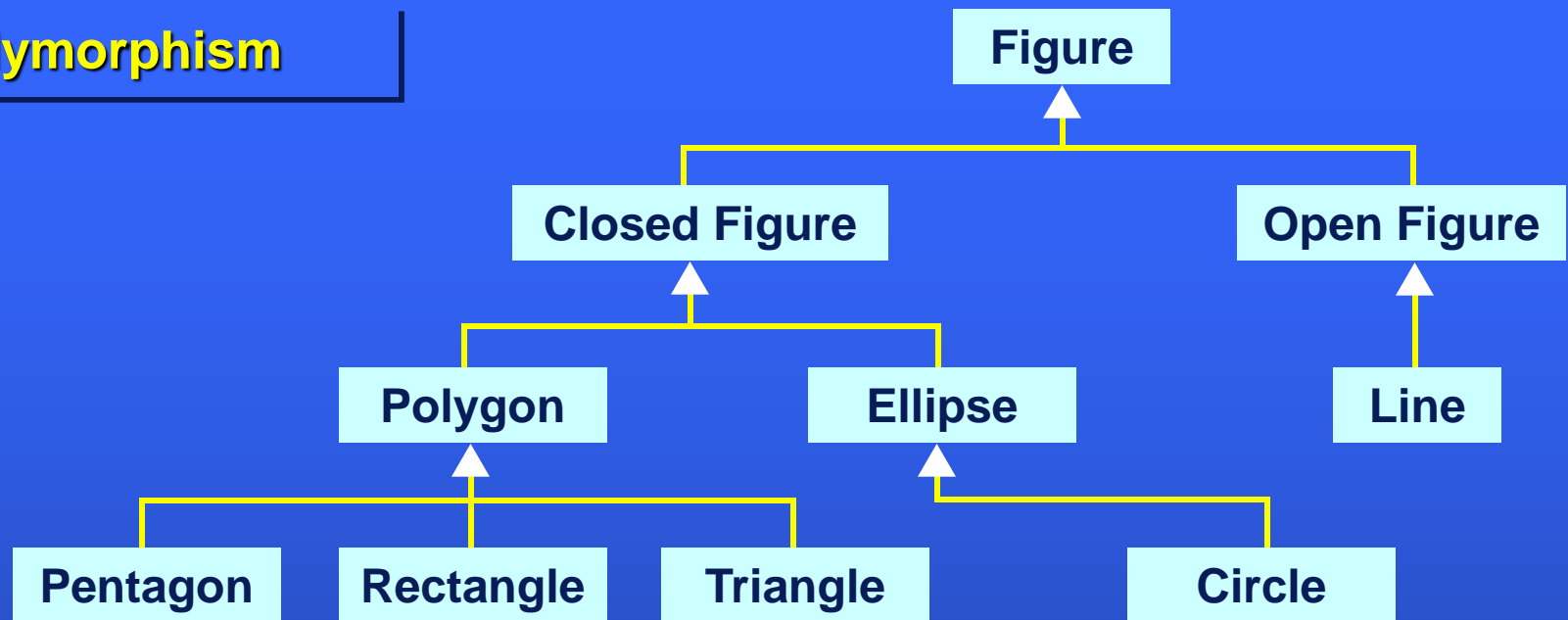
Encapsulation means that a consumer sees only the services that are available from an object, but not how those services are implemented.



Consumer / Supplier Viewpoints

- Only the supplier has visibility into the object's procedures and data.
- From a consumer's point of view, an object is a seamless capsule that offers a number of services, with no visibility as to how these services are implemented.

Polymorphism



- **Polymorphism** refers to the ability of an object to assume more than one form. For example, an object reference can be created to refer to a shape: `obj ref shape;`
- The object reference `shape` may refer to a rectangle, triangle, or circle depending on the logic at run time.
- For example, sending the `computeArea` message to the object pointed to by the object reference `shape` would invoke a different algorithm (procedure) depending on the form of that object, i.e., rectangle, triangle, or circle, at run time.

Dynamic Binding

- **Dynamic Binding** implies that the implementation code executed in responding to a particular message in the source code is not known at compile time, and is dispatched at run time depending on the form of the polymorphic object that receives the message. For example, an object reference can be created to refer to a shape:

```
obj ref  shape;
```

- The object reference `shape` may refer to, or can assume the form of, a circle, rectangle, or triangle.
- For example, sending the `computeArea` message to an object of the Circle class, pointed to by the object reference `shape`, would invoke a different algorithm from one invoked when sending `computeArea` to an object of the Rectangle class, again pointed to by the object reference `shape`.
- Therefore, the implementation code executed in response to the `computeArea` message is determined and **dynamically bound at run time** depending on the form of the object, pointed to by the object reference `shape`, which receives the message.
- Polymorphism and dynamic binding are strongly related.

Unified Modeling Language (UML) Diagrams for Object-Oriented Design Specification

■ Structural Diagrams

- **Class Diagram:** Classes, interfaces, and collaborations
- **Object Diagram:** Objects
- **Component Diagram:** Components
- **Deployment Diagram:** Nodes

■ Behavioral Diagrams

- **Use Case Diagram:** Organizes the behaviors of the system
- **Sequence Diagram:** Focused on the time ordering of messages
- **Collaboration Diagram:** Focused on the structural organization of objects that send and receive messages.
- **Statechart Diagram:** Focused on the changing state of a system driven by events
- **Activity Diagram:** Focused on the flow of control from activity to activity.